

# WiFi

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Connecting Arduinos to the internet

Enable native scrolling

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## ESP8266

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To connect the Arduinos to a WiFi network we will be using ESP8266 shields

We will be using [AT commands](#) to control the ESPs

The ESP8266 chips could also be programmed directly as they contain a microcontroller that is much more powerful than the Arduino

*Do not* reflash the ESP shields provided in the course

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Testing the shields

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## Testing

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To check if your shield is working correctly disconnect the USB-cable from your Arduino

```
1 esp_client.begin(  
2   &esp_serial, "GDI", "password",  
3   "192.168.42.42", 30303  
4 );
```

and copy [this](#) program into the Arduino IDE, scroll down to the setup function and adapt the IP address to one provided by your tutor

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## Testing

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Connect the RGB-Led to the pins on the WiFi-shield that will be plugged into the following Arduino pins:

**R** - 9 / **G** - 10 / **B** - 11 / GND - GND

Carefully plug the WiFi-shield into your Arduino and reconnect the USB-cable

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# Testing

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```
1 self.coro= aio.start_server(  
2     self.handle_client,  
3     None,  
4     30303,  
5     loop= self.loop  
6 )
```

Your Tutor is running [this](#) program, it provides a TCP-server for your Arduino to connect to  
It then sends periodic color updates to every Arduino connected

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The test code on the previous slides used a python server and an Arduino client

Arduino ---connects to--> Python

To prevent issues with firewalls and [NATs](#) from now on the Arduino will act as a server and  
the python code will connect to it

Python ---connects to--> Arduino

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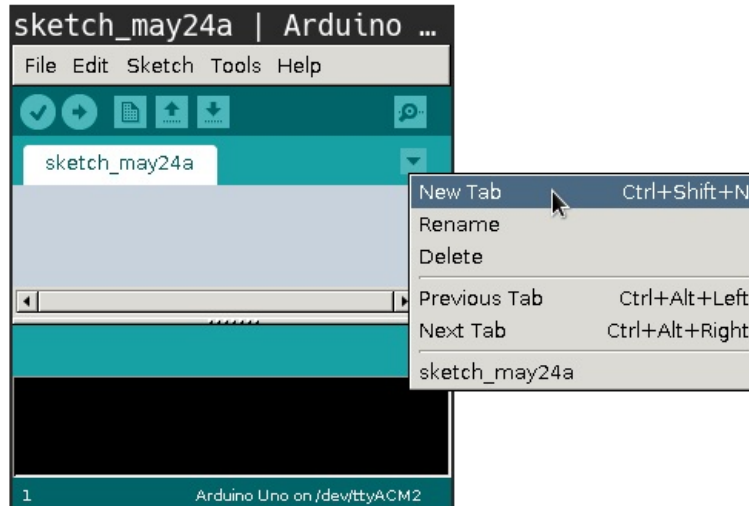
The following slides will provide you with an Arduino library to use the WiFi shield as a  
Server

The library allows exactly one connection and does not perform any error checking, this is  
why it is called DumbServer

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# DumbServer.cpp

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Use the "New Tab" option in the Arduino IDE to create the files `DumbServer.h` and `DumbServer.cpp`

Paste the contents of [DumbServer.h](#) / [DumbServer.cpp](#) into the respective files

Paste the content of [ServerExample.ino](#) into the main sketch file

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# DumbServer.cpp

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Flash the sketch to your Arduino and open the Serial Monitor

```
Starting server...  
...server is running  
My ip: 192.168.42.123
```

If the ESP was able to connect to the WiFi access point the Serial Monitor should display a message like the one above

We will be needing the IP-address that is shown later on

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# socket.py

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Open an interactive python session and enter the following commands

Replace the IP-address with the one found previously

```
1 import socket  
2  
3 s= socket.socket()  
4 s.connect(('192.168.42.123', 30303))  
5 s.setblocking(False)  
6  
7 s.send(b'Hello World\n')  
8  
9 s.recv(1024)
```

Check if the observed behaviour matches the Arduino sketch

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On the following slides you will see an example on how to work with sockets in a graphical program

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## sockets & GUIs

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```
1 while(esp_server.available()) {
2   String command= esp_server.readStringUntil('\n');
3   digitalWrite(13, (command == "on") ? HIGH : LOW);
4 }
```

...

Flash the code above onto your Arduino

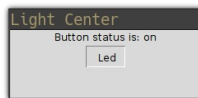
Connect Arduino pin 13 to an LED and pin 12 to GND

*Note:* DumbServer.h/.cpp are needed to compile the program

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## sockets & GUIs

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```
$ python3 22_light_center.py
Hostname: 192.168.42.123
Port: 30303
```

Run the [GUI code](#) and provide it with the correct IP-address

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